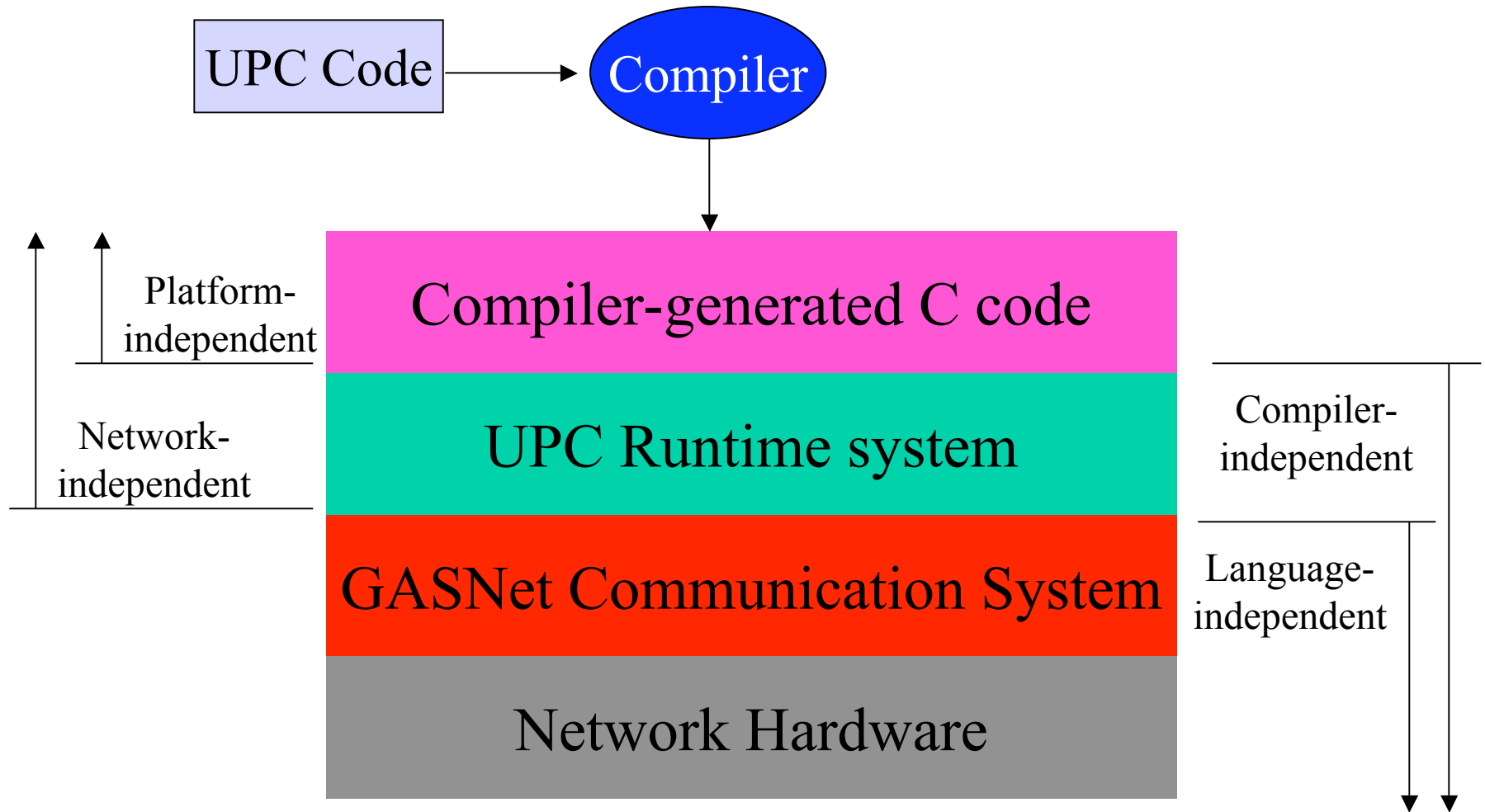# GASNet:
A Portable High-Performance Communication Layer for Global Address-Space Languages

Dan Bonachea, Mike Welcome,
Christian Bell, Paul Hargrove

NERSC/UPC Runtime System Organization

UPC Code → Compiler

Platform-independent

Network-independent

Compiler-independent

Language-independent

Compiler-generated C code

UPC Runtime system

GASNet Communication System
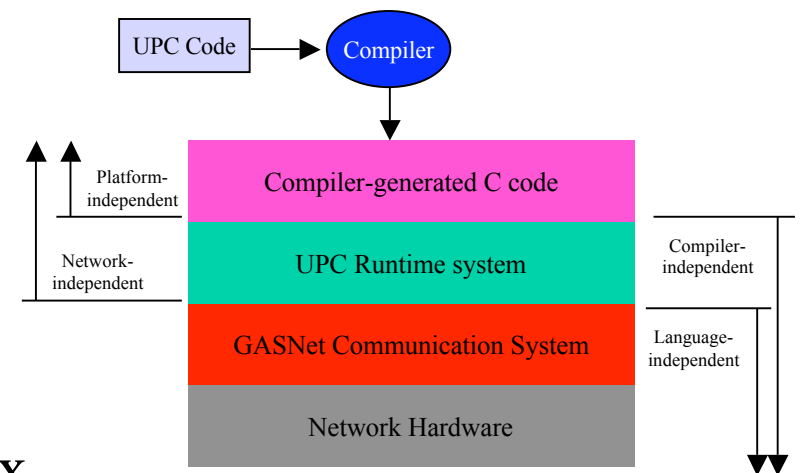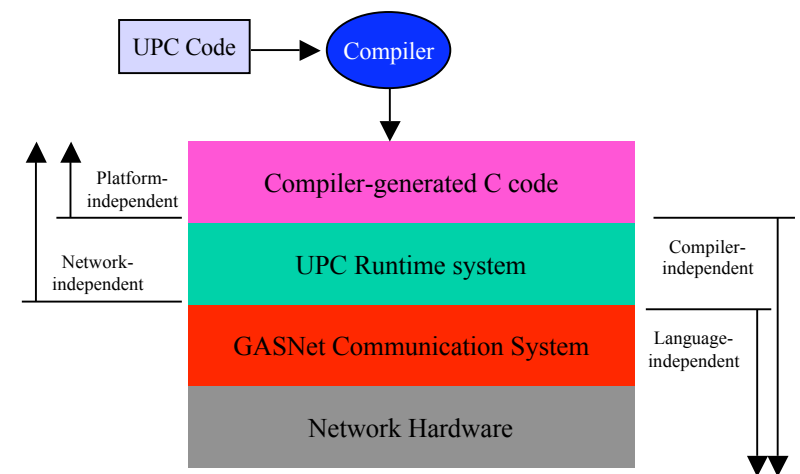
Network Hardware

GASNet Communication System- Goals

- Language-independence: Compatibility with several global-address space languages and compilers
  - UPC, Titanium, Co-array Fortran, possibly others..
  - Hide UPC- or compiler-specific details such as shared-pointer representation

- Hardware-independence: variety of parallel architectures & OS's
  - SMP: Origin 2000, Linux/Solaris multiprocessors, etc.
  - Clusters of uniprocessors: Linux clusters (myrinet, infiniband, via, etc)
  - Clusters of SMPs: IBM SP-2 (LAPI), Compaq Alphaserver, Linux CLUMPS, etc.

UPC Code → Compiler

Platform-independent

Network-independent

Compiler-generated C code

UPC Runtime system

GASNet Communication System

Network Hardware

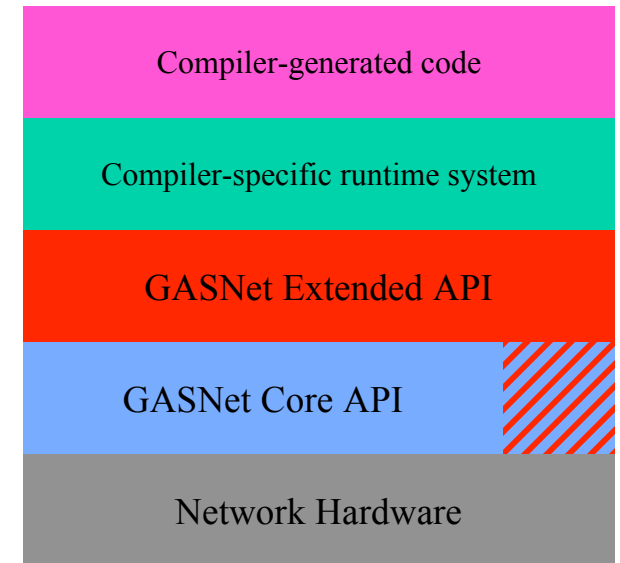Compiler-independent

Language-independent

GASNet Communication System- Goals (cont)

- Ease of implementation on new hardware

  – Allow quick implementations

  – Allow implementations to leverage performance characteristics of hardware

  – Allow flexibility in message servicing paradigm:

    - polling, interrupts, hybrids, etc

- Want both portability & performance

GASNet Communication System- Architecture

- 2-Level architecture to ease implementation:

- Core API
  - Most basic required primitives, as narrow and general as possible
  - Implemented directly on each platform
  - Based heavily on active messages paradigm

- Extended API
  - Wider interface that includes more complicated operations
  - We provide a reference implementation of the extended API in terms of the core API
  - Implementors can choose to directly implement any subset for performance - leverage hardware support for higher-level operations

| Compiler-generated code |
| Compiler-specific runtime system |
| GASNet Extended API |
| GASNet Core API |
| Network Hardware |

Progress to Date

- Designed & wrote the GASNet Specification
- Reference implementation of extended API
  - Written solely in terms of the core API
- Implemented a portable MPI-based core API
- **Completed native (core&extended) GASNet implementations for several high-performance networks:**
  - **Quadrics Elan (Dan)**
  - **Myrinet GM (Christian)**
  - **IBM LAPI (Mike)**
- **Did initial public release of GASNet**
- **Implementation under-way for Infiniband (Paul)**
  - **other networks under consideration**

Core API – Active Messages

- ## Super-Lightweight RPC
  - Unordered, reliable delivery
  - Matched request/reply serviced by "user"-provided lightweight handlers
  - General enough to implement almost any communication pattern
- ## Request/reply messages
  - 3 sizes: short (<=32 bytes),medium (<=512 bytes), long (DMA)
- ## Very general - provides extensibility
  - Available for implementing compiler-specific operations
  - scatter-gather or strided memory access, remote allocation, etc.
- ## AM previously implemented on a number of interconnects
  - MPI, LAPI, UDP/Ethernet, Via, Myrinet, and others
- ## Includes mechanism for explicit atomicity control in handlers
  - Even in the presence of interrupts & multithreading
  - Handler-safe locks & no-interrupt sections

Extended API – Remote memory operations

- Orthogonal, expressive, high-performance interface
  - Gets & Puts for Scalars and Bulk contiguous data
  - Blocking and non-blocking (returns a handle)
  - Also have a non-blocking form where the handle is implicit
- Non-blocking synchronization
  - Sync on a particular operation (using a handle)
  - Sync on a list of handles (some or all)
  - Sync on all pending reads, writes or both (for implicit handles)
  - Sync on operations initiated in a given interval
  - Allow polling (trysync) or blocking (waitsync)
- Useful for experimenting with a variety of parallel compiler optimization techniques

Extended API – Remote memory operations

- API for remote gets/puts:

```
void    get     (void *dest, int node, void *src, int numbytes)
handle  get_nb  (void *dest, int node, void *src, int numbytes)
void    get_nbi (void *dest, int node, void *src, int numbytes)

void    put     (int node, void *src, void *dest, int numbytes)
handle  put_nb  (int node, void *src, void *dest, int numbytes)
void    put_nbi (int node, void *src, void *dest, int numbytes)
```

- "nb"/"nbi" = non-blocking with explicit/implicit handle
- Also have "value" forms that are register-memory, and "bulk" forms optimized for large memory transfers
- Extensibility of core API allows easily adding other more complicated access patterns (scatter/gather, strided, etc)

Extended API – Remote memory operations

- API for get/put synchronization:
- Non-blocking sync with explicit handles:

```
int  try_syncnb(handle)
void wait_syncnb(handle)


int  try_syncnb_some(handle *, int numhandles)
void wait_syncnb_some(handle *, int numhandles)
int  try_syncnb_all(handle *, int numhandles)
void wait_syncnb_all(handle *, int numhandles)
```

- Non-blocking sync with implicit handles:

```
int  try_syncnbi_gets()
void wait_syncnbi_gets()
int  try_syncnbi_puts()
void wait_syncnbi_puts()
int  try_syncnbi_all()  // gets & puts
void wait_syncnbi_all()
```
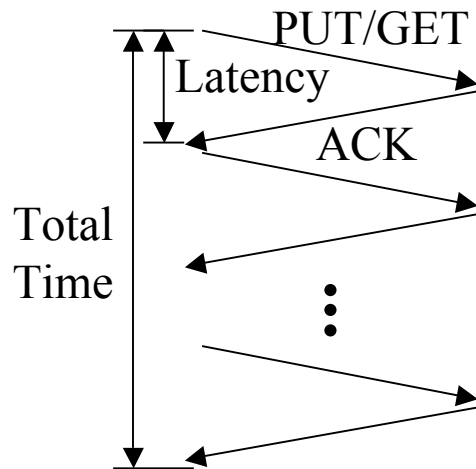
Code Generation Tradeoffs

- Blocking vs. Non-blocking puts/gets
- Put/Get variety: non-bulk vs. bulk
  - optimized for small scalars vs large zero-copy
  - difference in semantics - put src, alignment
- Put/Get synchronization mechanism
  - expressiveness/complexity tradeoffs
  - explicit handle vs. implicit handle, access regions
- Work remains to explore these tradeoffs in the context of code generation
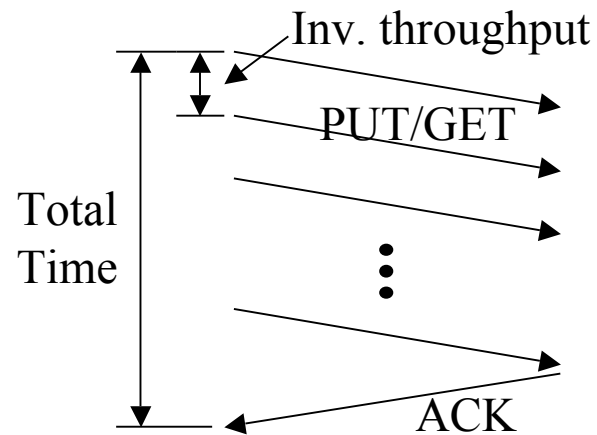
Performance Results

Experiments

- ## Micro-Benchmarks: ping-pong and flood

Ping-pong
round-trip latency test

Flood bandwidth test

PUT/GET

Latency

ACK

Total
Time

Round-trip Latency =
Total time / iterations

Inv. throughput

PUT/GET

Total
Time

ACK

Inv. throughput = Total time / iterations
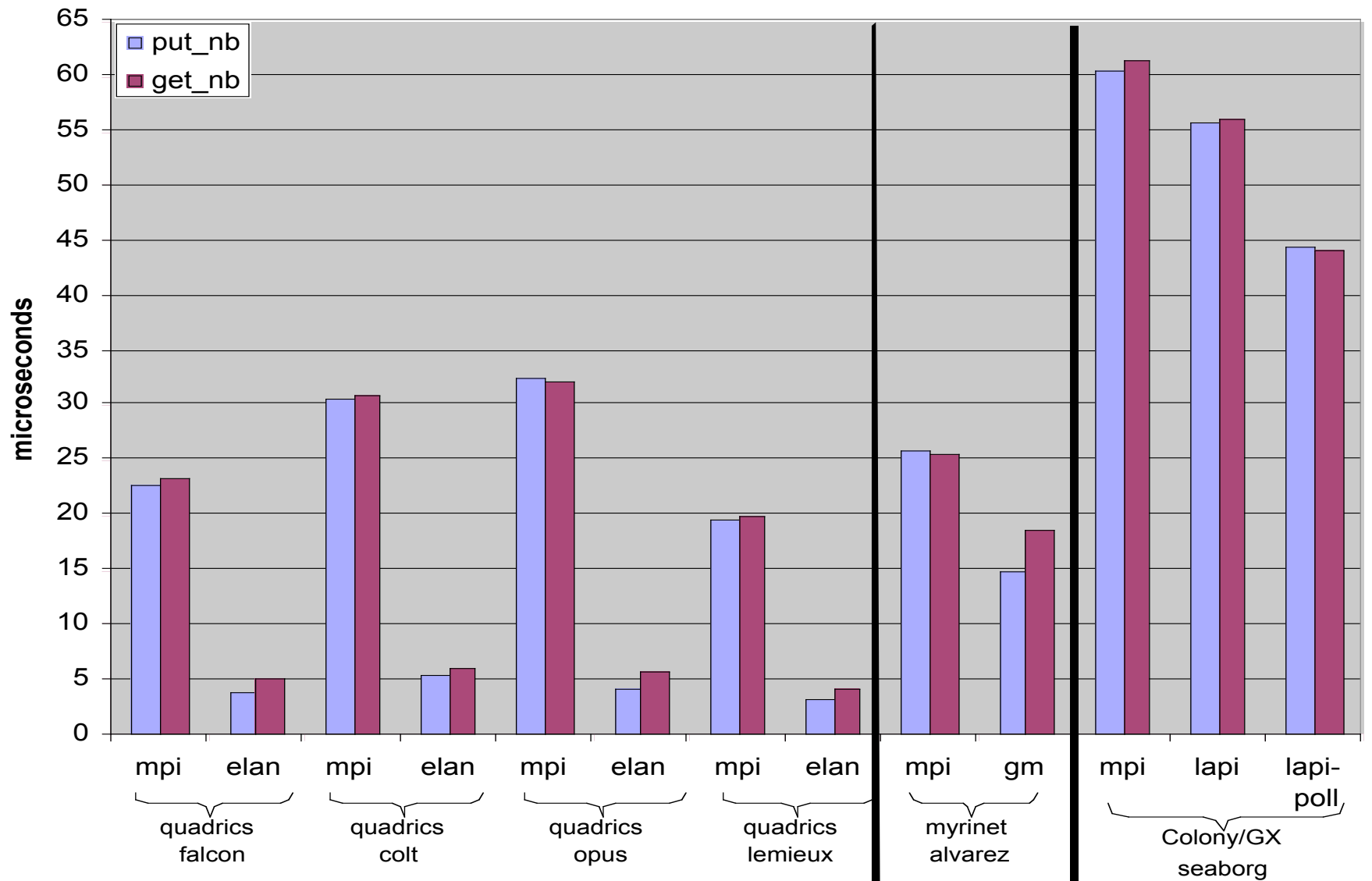BW = msg size * iter / total time

GASNet Configurations Tested

- Quadrics (elan):
    - mpi-refext - AMMPI core, AM-based puts/gets
    - elan-elan - pure native elan implementation
- Myrinet (GM):
    - mpi-refext - AMMPI core, AM-based puts/gets
    - gm-gm - pure native GM implementation
- IBM SP (LAPI):
    - mpi-refext - AMMPI core, AM-based puts/gets
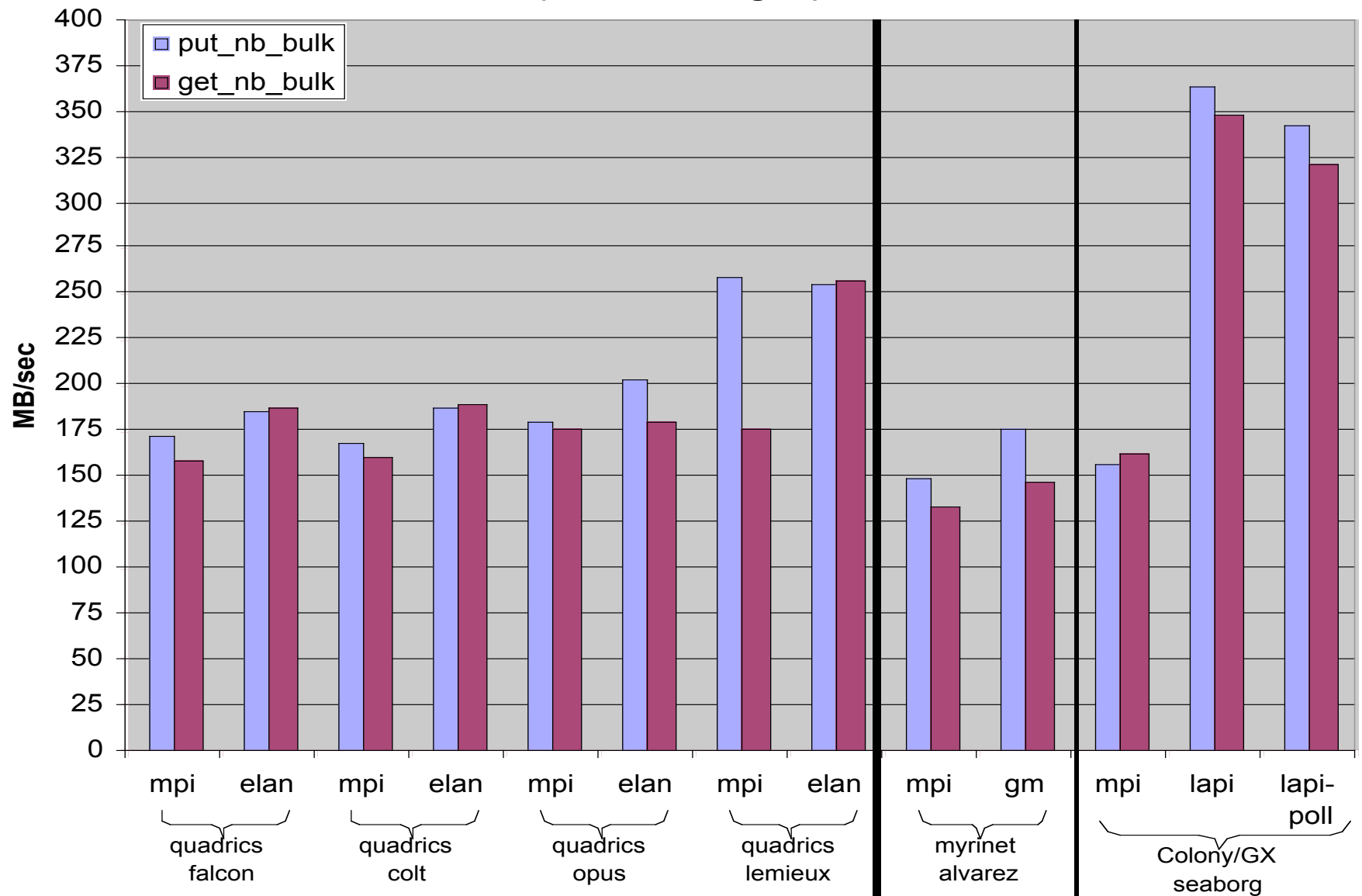   - lapi-lapi - pure native LAPI implementation

System Configurations Tested

- Quadrics - falcon/colt (ORNL)
  - Compaq Alphaserver SC 2.0, ES40 Elan3, single-rail
  - 64-node, 4-way 667 MHz Alpha EV67, 2GB, libelan1.2/1.3, OSF 5.1
- Quadrics - lemieux (PSC)
  - Compaq Alphaserver SC, ES45 Elan3, double-rail (only tested w/single)
  - 750-node, 4-way 1GHz Alpha, 4GB, libelan1.3, OSF 5.1
- Quadrics - opus (PNL)
  - Itanium-2 Cluster, Elan3, double-rail (only tested w/single)
  - 128-node, 2-way 1GHz Itanium-2, 12GB, libelan1.4, Redhat Linux 7.2
- Myrinet - Alvarez (NERSC)
  - x86 Cluster, 33Mhz 64-bit Myrinet 2000 PCI64C, 200 MHz Lanai 9.2
  - 80-node, 2-way 866 Mhz P3, 1GB, GM 1.5.1, Redhat Linux 7.2
  - Empirical PCI bus bandwidth: 229MB/sec read, 245 MB/sec write
- LAPI - seaborg (NERSC)
  - IBM RS/6000 SP Power3, Colony-GX network
  - 380-node, 16-way 375MHz Power3, 64GB, 64KB L1, 8MB L2, AIX 5.1

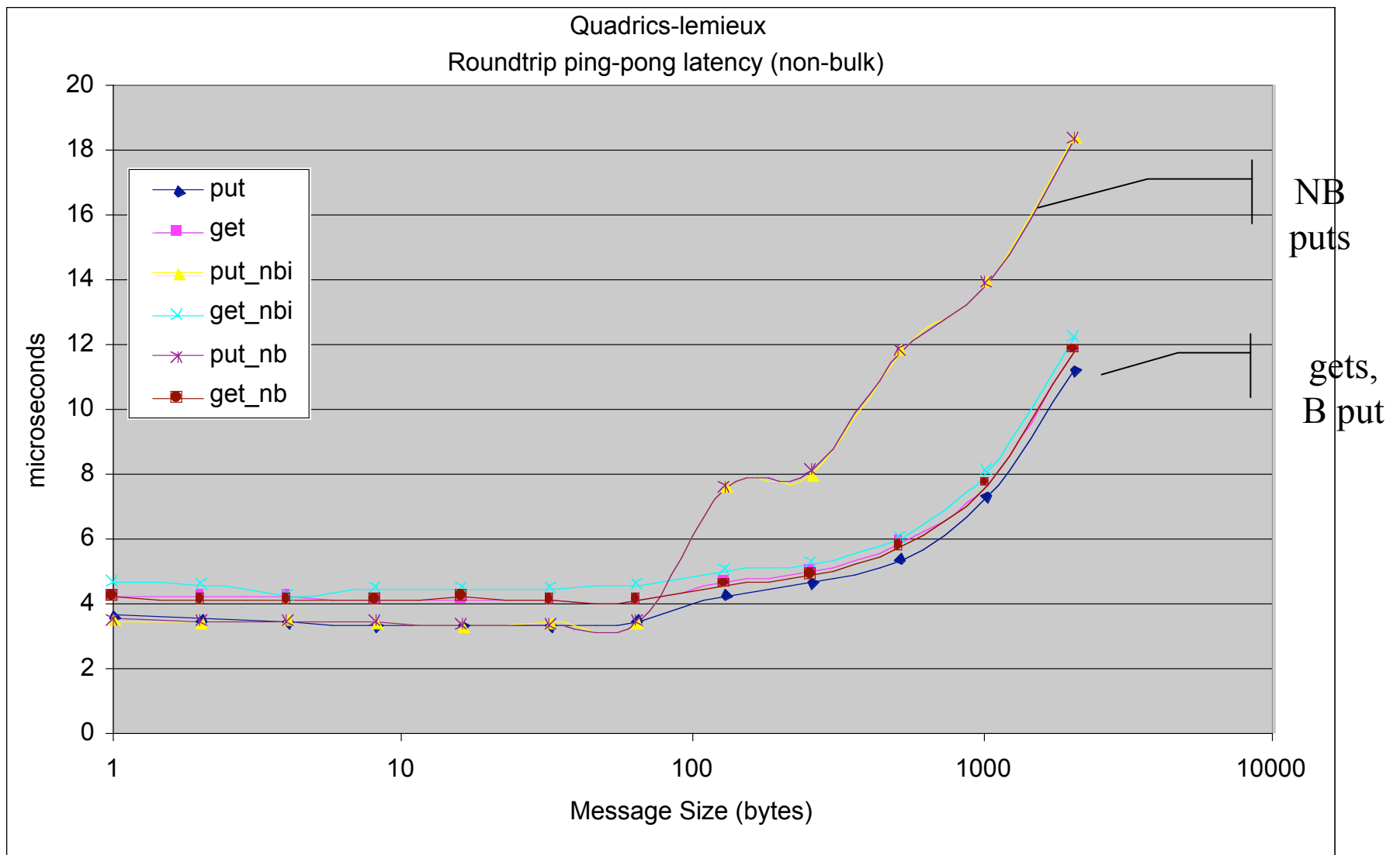**GASNet Put/Get Roundtrip Latency (min over msg sz)**

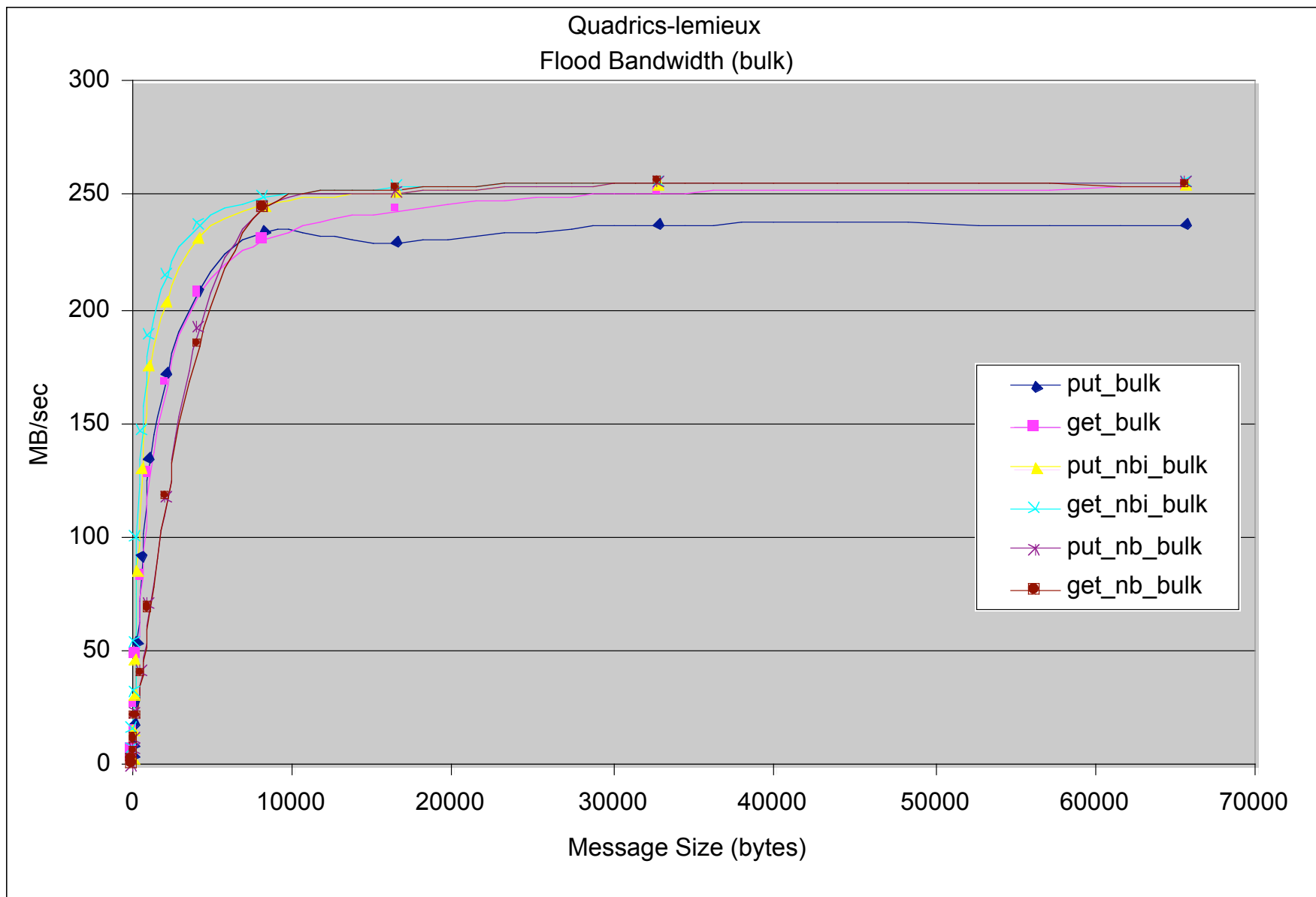**GASNet Put/Get Bulk Flood Bandwidth (max over msg sz)**

Quadrics elan-conduit

- Implementation based on elan-lib
  - the "portable" Quadrics API (will be supported on elan4)
- Core API
  - Polling-based implementation on elan queue API and TPORTS API
  - Uses zero-copy elan RDMA puts for AM Long msgs
- Extended API
  - Put/get implemented using zero-copy elan RDMA puts/gets in the common case
  - Some uncommon cases require bounce buffers or active messages as fallback
  - Barriers implemented using Quadrics hardware barrier for anonymous barriers, or broadcast/barrier for named

Empirical round-trip latency of hardware: ~3.4 us

Theoretical peak bandwidth of NIC hardware: 340 MB/sec
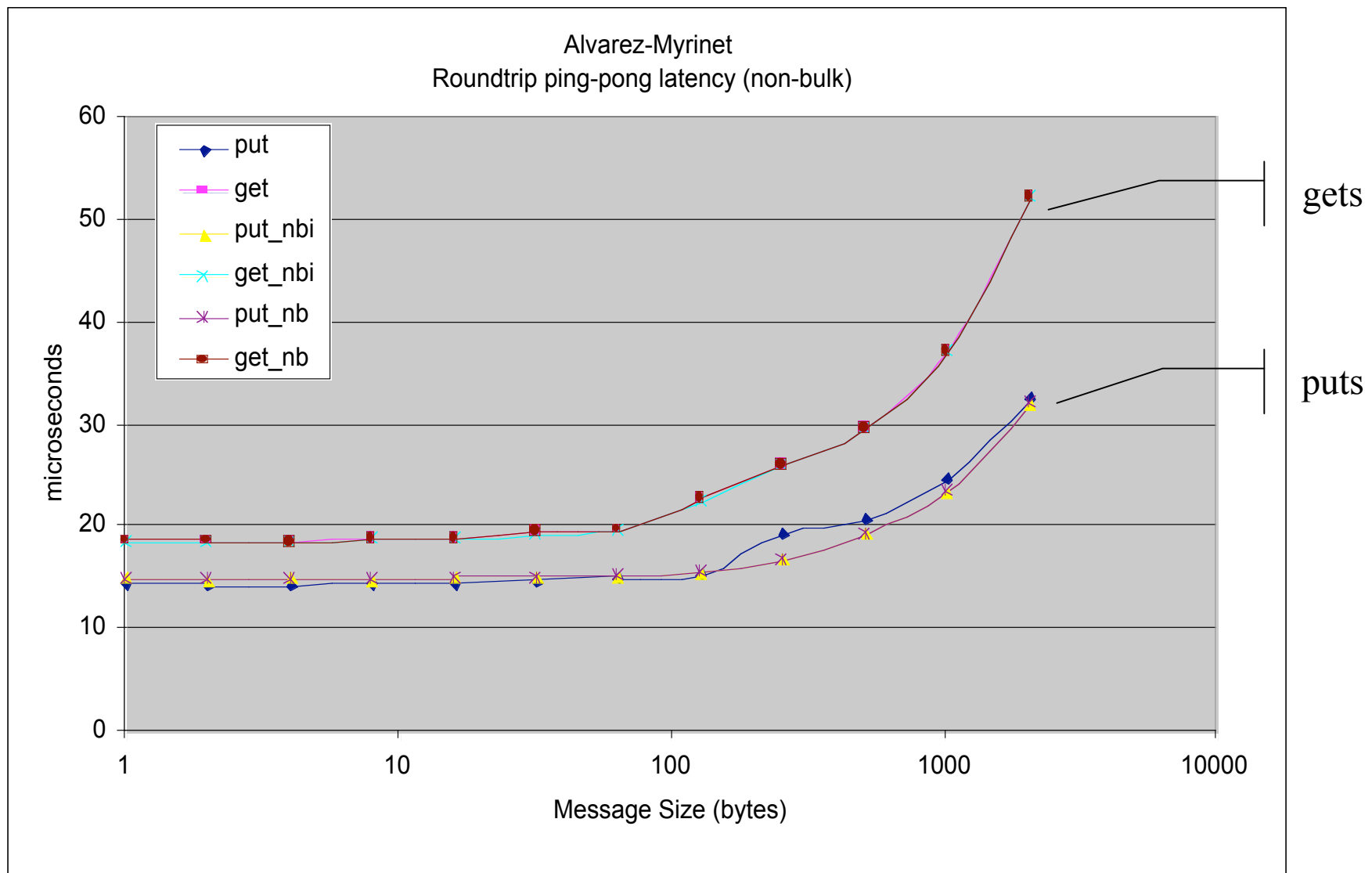
Quadrics elan-conduit: Future work

- Work-around or resolve some problems encountered in Quadrics elan-lib software
  - dual-rail operation
  - loopback on SMP nodes sharing a NIC
- Further performance tuning
  - based on feedback from app experience
  - implement split-phase barrier on NIC processor
- Continued maintenance with new versions of elanlib
  - new elan4 hardware expected soon
- We'd really like some Quadrics hardware of our own to play with! :)

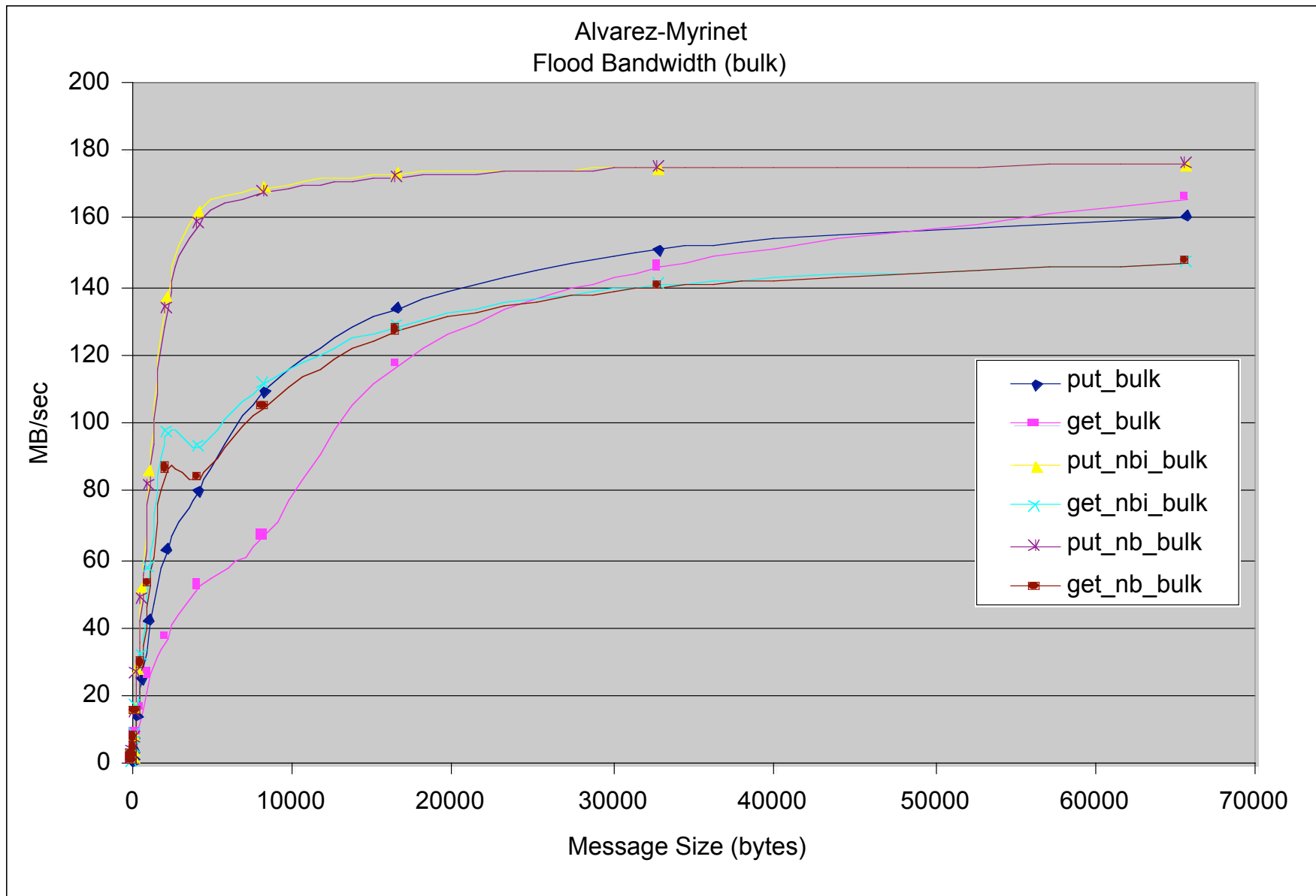# Myrinet gm-conduit

- Work done by Christian Bell
- Initial Core API implementation took 2 weeks
  - AM implementation fairly straightforward over GM for Small/Medium AMs
  - Long/LongAsync AMs required more work for DMA support (addressed in extended API and Firehose algorithm)
  - Polling-based conduit (currently)
  - Under threaded GASNet configuration (PAR), allows for concurrent handler execution

Myrinet gm-conduit

- Extended API took 1 month
  - Proposed and published a new algorithm, Firehose algorithm, to improve performance of one-sided operations over pinning-based networks (GM, Infiniband) (to be presented at CAC '03)
  - One-sided operations used for bulk and non-bulk puts
  - Gets currently use an AM with a one-sided put (GM 2.0 will add one-sided gets)
- Bootstrapping problem
  - Each Myrinet site must develop a custom bootstrapper or use 3rd-party solutions (Millennium nightmare)
  - GM conduit provides bootstrapping support for both dedicated (PBS) and non-dedicated (gexec) cluster configurations.

Empirical round-trip latency of hardware: ~17 us

Empirical peak bandwidth of hardware: ~210 MB/sec (puts only)

Myrinet gm-conduit

- Future
  - More efforts in tuning Firehose algorithm
  - Support for GM 2.0 and one-sided gets
  - Hooks for minimal interrupt support
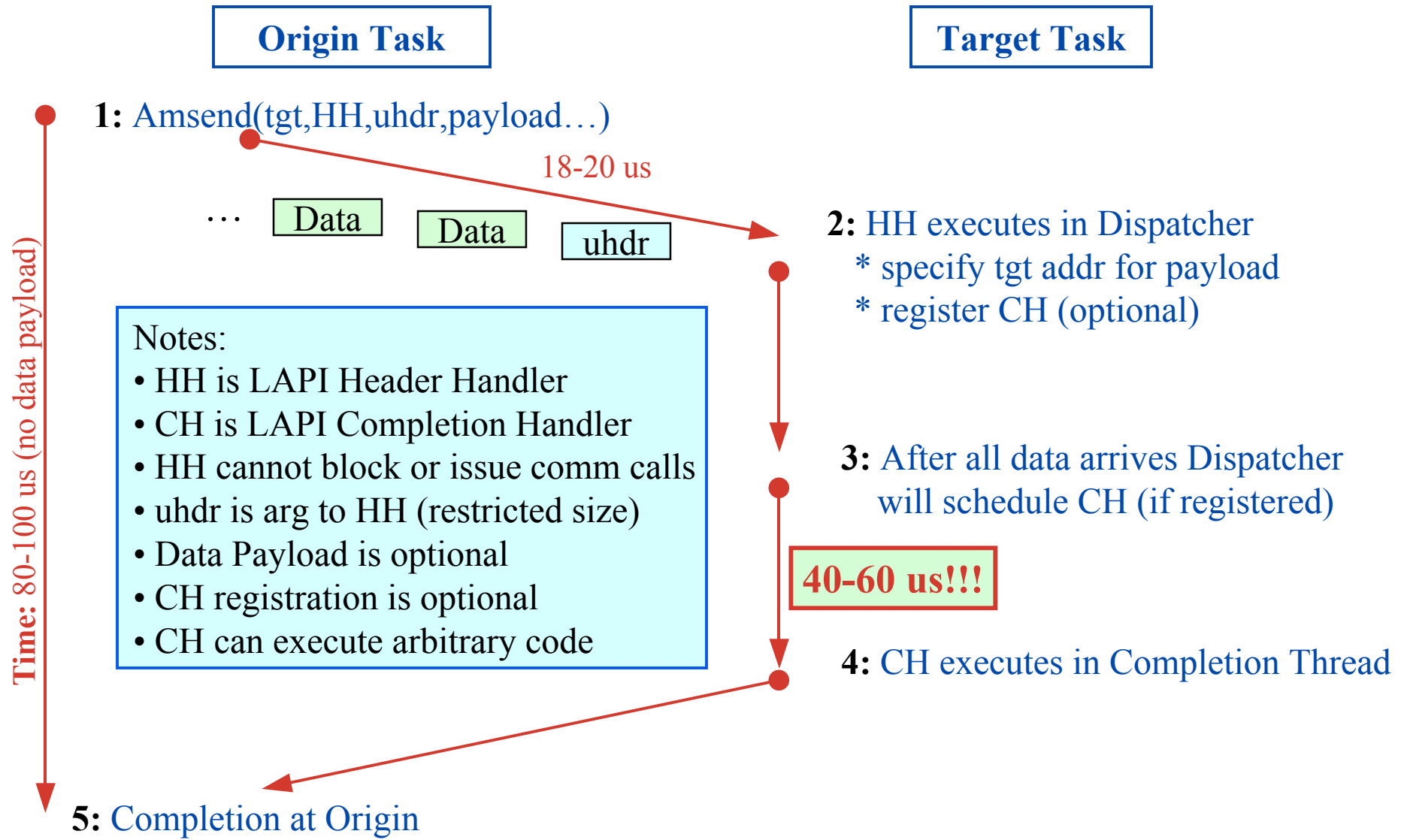 - Continued bootstrapping support

GASNet/LAPI for IBM SP

- Initial (non-optimized) implementation took 2 weeks
  - Use of GASNet conduit template provided simple implementation framework
  - GASNet PUT/GET Implemented using LAPI PUT/GET
  - GASNet AM Request/Reply and Barriers implemented using LAPI AMs
  - Non-blocking Sync methods implemented using LAPI counters
  - Handler Safe Locks implemented using Pthread mutex
  - No-Interrupt sections a No-op
  - No memory registration issues
- 3 weeks for Active Message optimizations
- LAPI Conduit can run in Interrupt or Polling mode

GASNet/LAPI: AM Optimizations

- Optimizations only apply to GASNet operations implemented using LAPI AM
  - Specifically GASNet AM and Barrier operations
  - Not needed for GASNet PUT/GET
- GASNet token caching and re-use to reduce allocation overhead
- Packing small message payload into LAPI AM Header Handler argument to reduce GASNet AM latency.
- Implementation of "Ready Queue" for quick execution of GASNet AM Request/Reply handlers
  - Eliminate 40-60 usec latency to schedule LAPI Completion Handler
  - "Ready" handlers executed by main thread while polling

LAPI AM: Execution Flow

Origin Task

Target Task

1: Amsend(tgt,HH,uhdr,payload…)

18-20 us

… Data   Data   uhdr

Time: 80-100 us (no data payload)

Notes:
- HH is LAPI Header Handler
- CH is LAPI Completion Handler
- HH cannot block or issue comm calls
- uhdr is arg to HH (restricted size)
- Data Payload is optional
- CH registration is optional
- CH can execute arbitrary code

2: HH executes in Dispatcher
* specify tgt addr for payload
* register CH (optional)

3: After all data arrives Dispatcher will schedule CH (if registered)

40-60 us!!!

4: CH executes in Completion Thread

5: Completion at Origin

LAPI seaborg (polling)
Roundtrip ping-pong latency (non-bulk)

Empirical round-trip latency of hardware: ~42 us

LAPI seaborg (polling)
Flood Bandwidth (bulk)

Legend:
- put_bulk
- get_bulk
- put_nbi_bulk
- get_nbi_bulk
- put_nb_bulk
- get_nb_bulk

Y-axis: MB/sec
X-axis: Message Size (bytes)

Empirical peak bandwidth of hardware: ~350 MB/sec

GASNet/LAPI: Future Work

- Possible Future Optimizations:
  - Reduce/Eliminate locking overhead (costly on SP)
    - Token allocation
    - Access to "Ready Queue"
  - Improve Split-phase Barrier implementation
    - Broadcast Tree?
    - Implement as blocking barrier using LAPI_Gfence?
  - Throttle NB PUT/GET to avoid performance drop-off

- Future LAPI may allow restricted communication in HH
  - Would eliminate need for ready queue or CH for small message GASNet Request AM
  - NOTE: IBM will use this (future) LAPI version to re-implement MPI

Conclusions

GASNet provides a portable & high-performance interface for implementing GAS languages

- two-level design allows rapid prototyping & careful tuning for hardware-specific network capabilities

- We have a fully portable MPI-based implementation of GASNet, several native implementations (Myrinet, Quadrics, LAPI) and other implementations on the way (Infiniband)

- Performance results are very promising
  - Overheads of GASNet are low compared to underlying network
  - Interface provides the right primitives for use as a compilation target, to support advanced compiler communication scheduling

Future Work

- Further tune our native GASNet implementations
- Implement GASNet on new interconnects
  - Infiniband, Cray T3E, Dolphin SCI, SGI SHMEM, Cray X-1…
- Implement GASNet on other portable interfaces
  - UDP/Ethernet, ARMCI…
- Augment Extended API with other useful functions
  - Collective communication
    - broadcast, reduce, all-to-all
    - interface to be based on UPC Collective spec & Titanium collective ops
  - More sophisticated memory access ops
    - strided, scatter/gather (indexed put/get)
    - interface to be based on ARMCI and Titanium ops
- Network benchmarking based on GASNet (Paul)

More Future Work

- Collaborate with ARMCI effort
    - GASNet-over-ARMCI / or using ARMCI
- Potential External Collaborations
    - (Go)DIVA HPCS Darpa project, Quadrics, others..
- Implement some small, real applications directly on GASNet
    - Experiment with the interface to gain further insights into good code-generation strategies
    - Gather some app-level performance results

Extra Slides

Introduction

- Two major paradigms for parallel programming
  - Shared Memory
    - single logical memory space, loads and stores for communication
    - ease of programming
  - Message Passing
    - disjoint memory spaces, explicit communication
    - often more scalable and higher-performance
- Another Possibility: Global-Address Space (GAS) Languages
  - Provide a global shared memory abstraction to the user, regardless of the hardware implementation
  - Make distinction between local & remote memory explicit
  - Get the ease of shared memory programming, and the performance of message passing
  - Examples: UPC, Titanium, Co-array Fortran, …
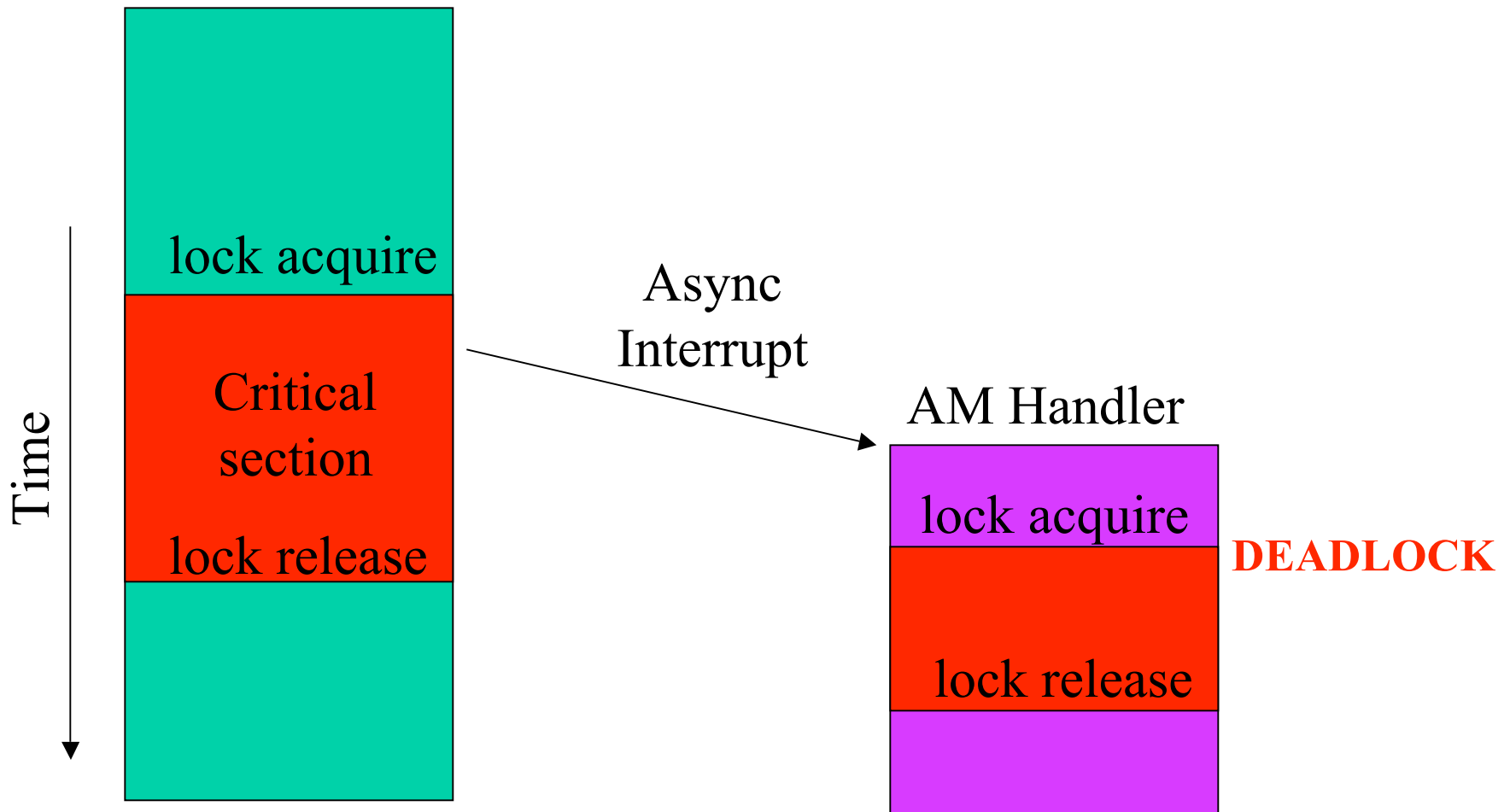
The Case for Portability

- Most current UPC compiler implementations generate code directly for the target system
  - Requires compilers to be rewritten from scratch for each platform and network

- We want a more portable, but still high-performance solution
  - Want to re-use our investment in compiler technology across different platforms, networks and machine generations
  - Want to compare the effects of experimental parallel compiler optimizations across platforms
  - The existence of a fully portable compiler helps the acceptability of UPC as a whole for application writers

Core API – Atomicity Support for Active Messages

- Atomicity in traditional Active Messages:
  - handlers run atomically wrt. each other & main thread
  - handlers never allowed block (e.g. to acquire a lock)
  - atomicity achieved by serializing everything (even when not reqd)
- Want to improve concurrency of handlers
- Want to support various handler servicing paradigms while still providing atomicity
  - Interrupt-based or polling-based handlers, NIC-thread polling
  - Want to support multi-threaded clients on an SMP
  - Want to allow concurrency between handlers on an SMP
- New Mechanism: Handler-Safe Locks
  - Special kind of lock that is safe to acquire within a handler
    - HSL's include a set of usage constraints on the client and a set of implementation guarantees which make them safe to acquire in a handler
  - Allows client to implement critical sections within handlers

Why interrupt-based handlers cause problems

App. Thread

Analogous problem if app thread makes a synchronous network call (which may poll for handlers) within the critical section

Handler-Safe Locks

- HSL is a basic mutex lock
  - imposes some additional usage rules on the client
  - allows handlers to safely perform synchronization
- HSL's must always be held for a "bounded" amount of time
  - Can't block/spin-wait for a handler result while holding an HSL
  - Handlers that acquire them must also release them
  - No synchronous network calls allowed while holding
  - AM Interrupts disabled to prevent asynchronous handler execution
- Rules prevent deadlocks on HSL's involving multiple handlers and/or the application code
  - Allows interrupt-driven handler execution
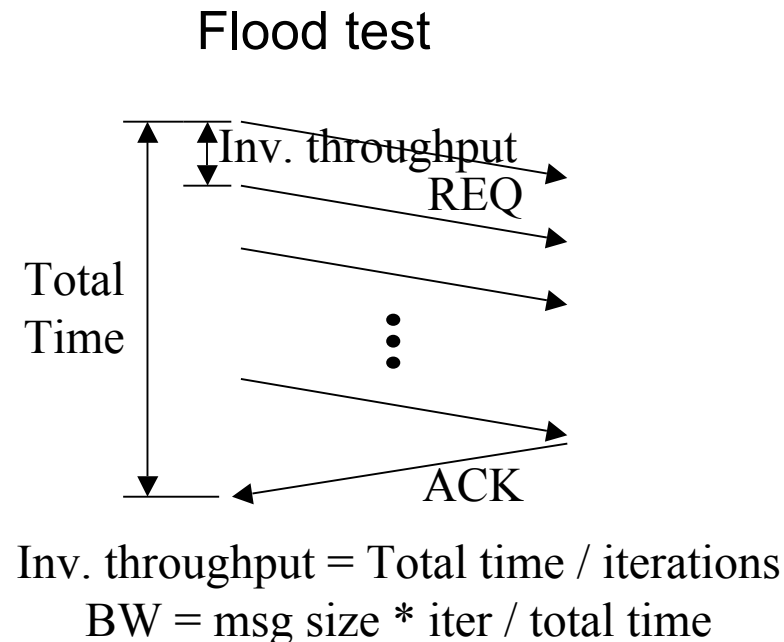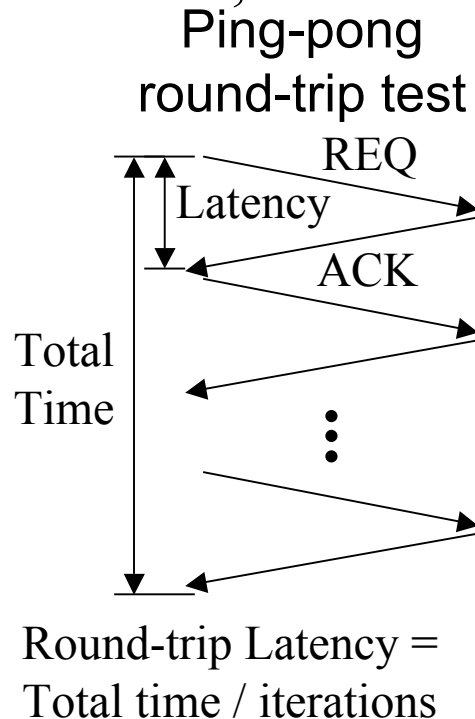 - Allows multiple threads to concurrently execute handlers

No-Interrupt Sections

- Problem:
  - Interrupt-based AM implementations run handlers asynchronously wrt. main computation (e.g. from a UNIX signal handler)
  - May not be safe if handler needs to call non-signal-safe functions (e.g. malloc)

- Solution:
  - Allow threads to temporarily disable interrupt-based handler execution: hold_interrupts(), resume_interrupts()
  - Wrap any calls to non-signal safe functions in a no-interrupt section
  - Hold & resume can be implemented very efficiently using 2 simple bits in memory (interruptsDisabled bit, messageArrived bit)
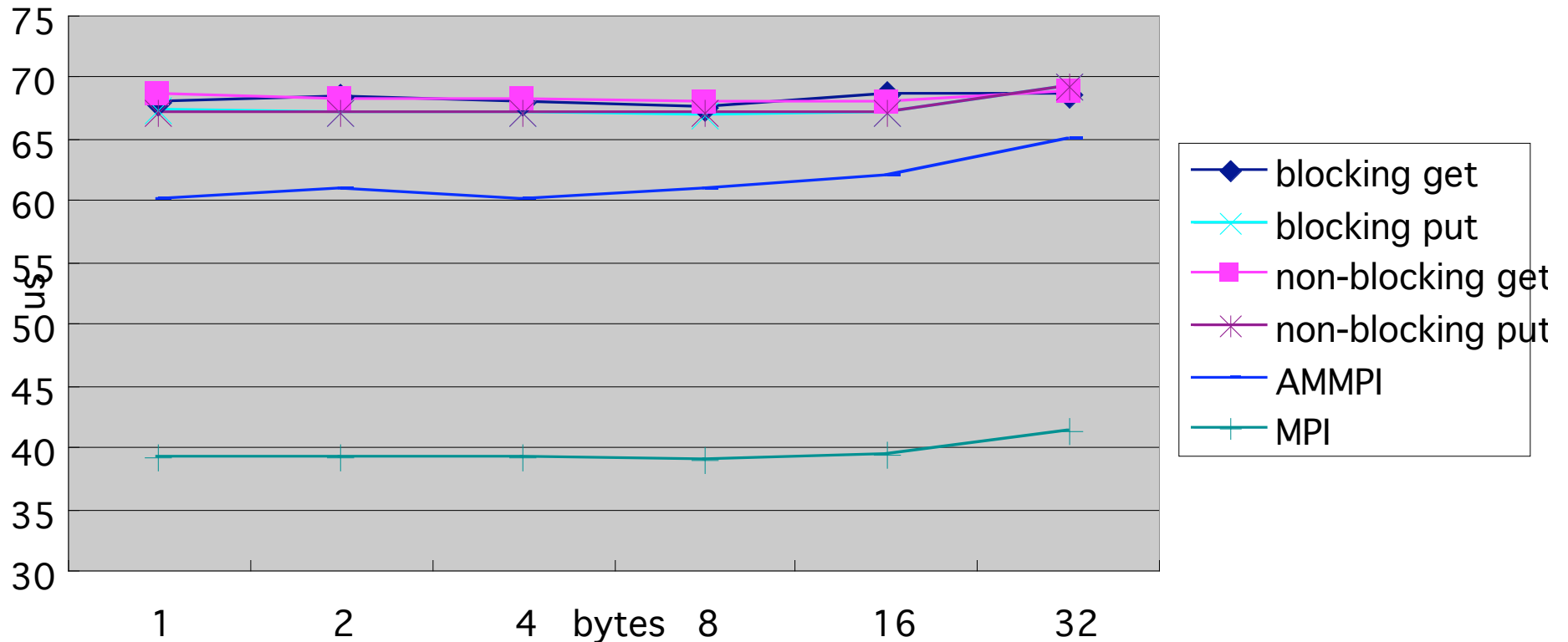
Performance Benchmarking of prototype MPI-based GASNet core (built on pre-existing AM-MPI)

Experiments

- Experimental Platform: IBM SP Seaborg
- Micro-Benchmarks: ping-pong and flood
- Comparison
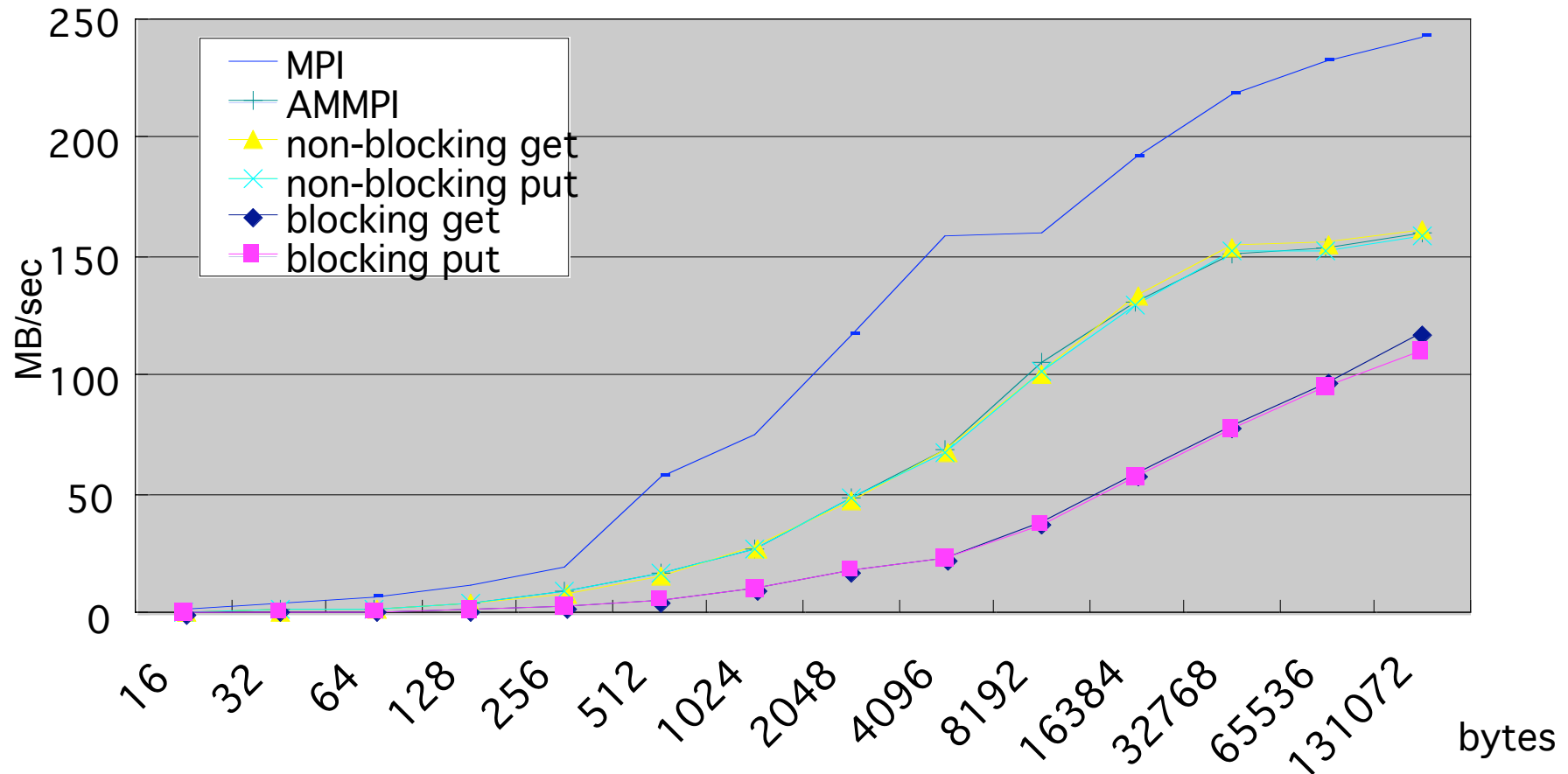 - blocking get/put, non-blocking get/put (explicit and implicit)
  - AMMPI, MPI

Ping-pong round-trip test

Flood test

REQ

Latency

ACK

Total Time

Inv. throughput

REQ

Total Time

ACK

Round-trip Latency = Total time / iterations

Inv. throughput = Total time / iterations
BW = msg size * iter / total time

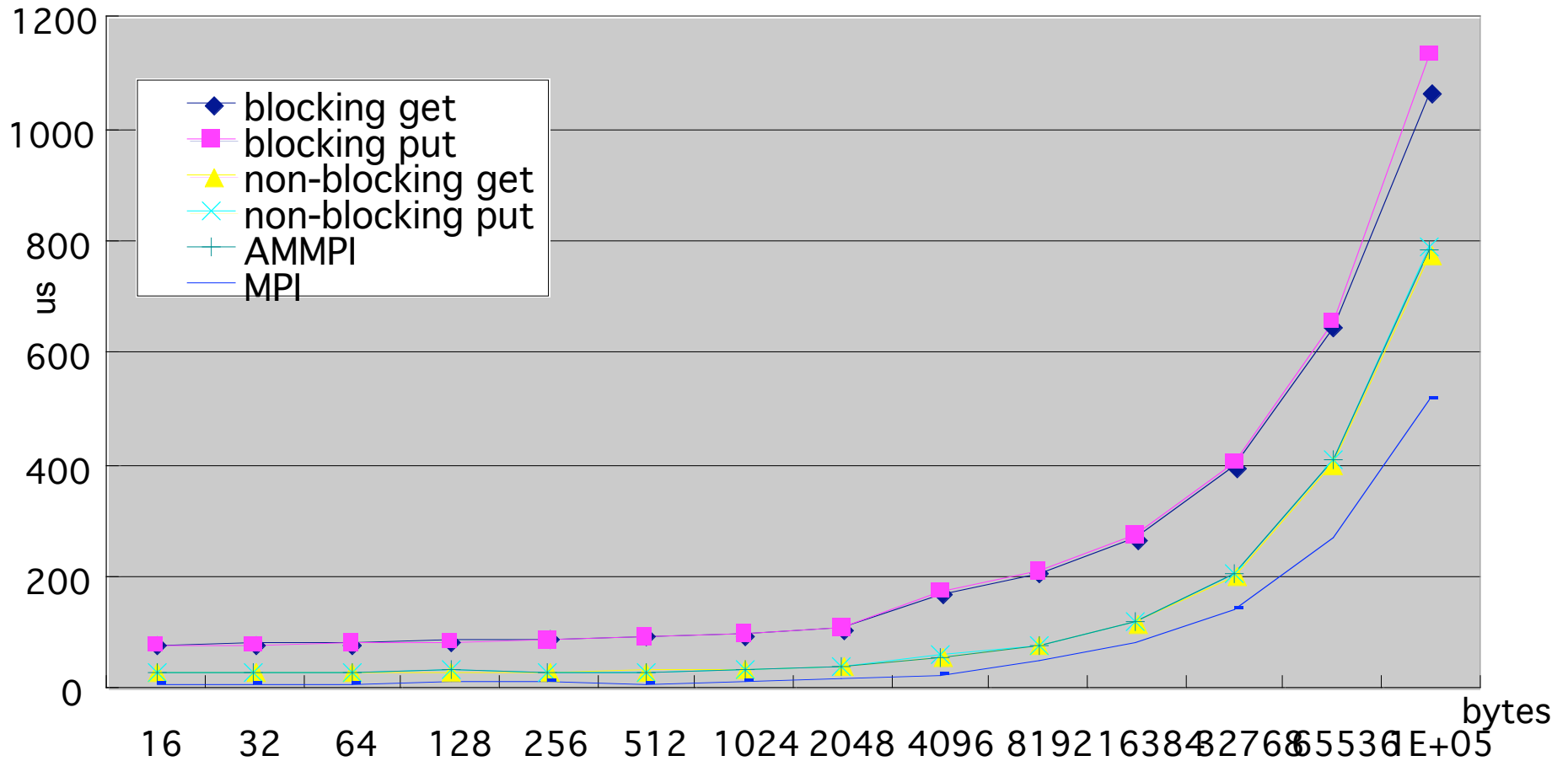# Latency (IBM SP, network depth = 8)

- Additional overhead of get/puts over AMMPI: 7 us
- Blocking and non-blocking get/puts equivalent
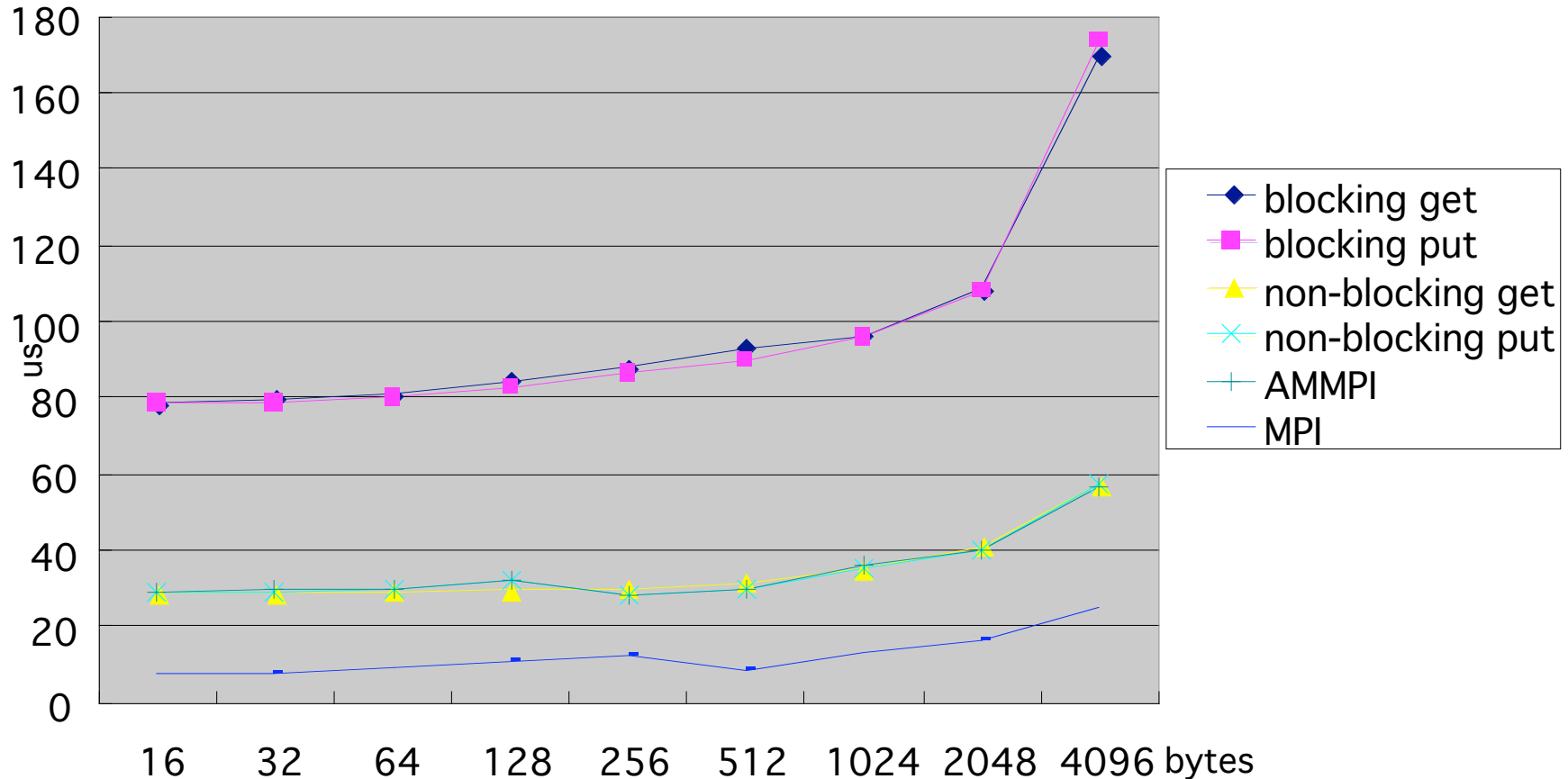
Bandwidth (IBM SP, network depth = 8)

- Non-blocking get/puts performed as well as AMMPI
- Non-blocking get/puts are benefited from overlap

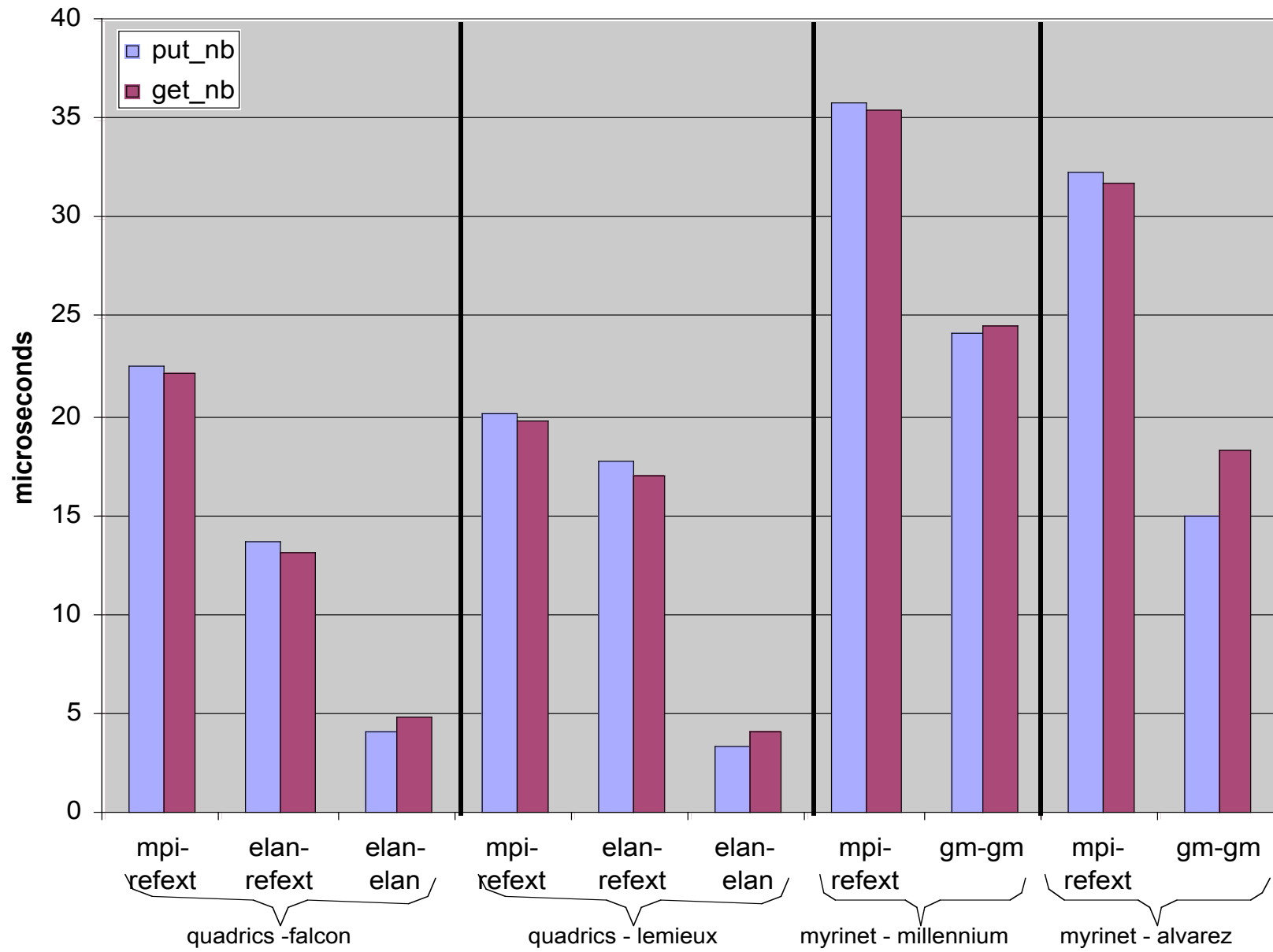# Inv. Throughput (IBM SP, network depth = 8)

- Non-blocking get/puts performed as well as AMMPI

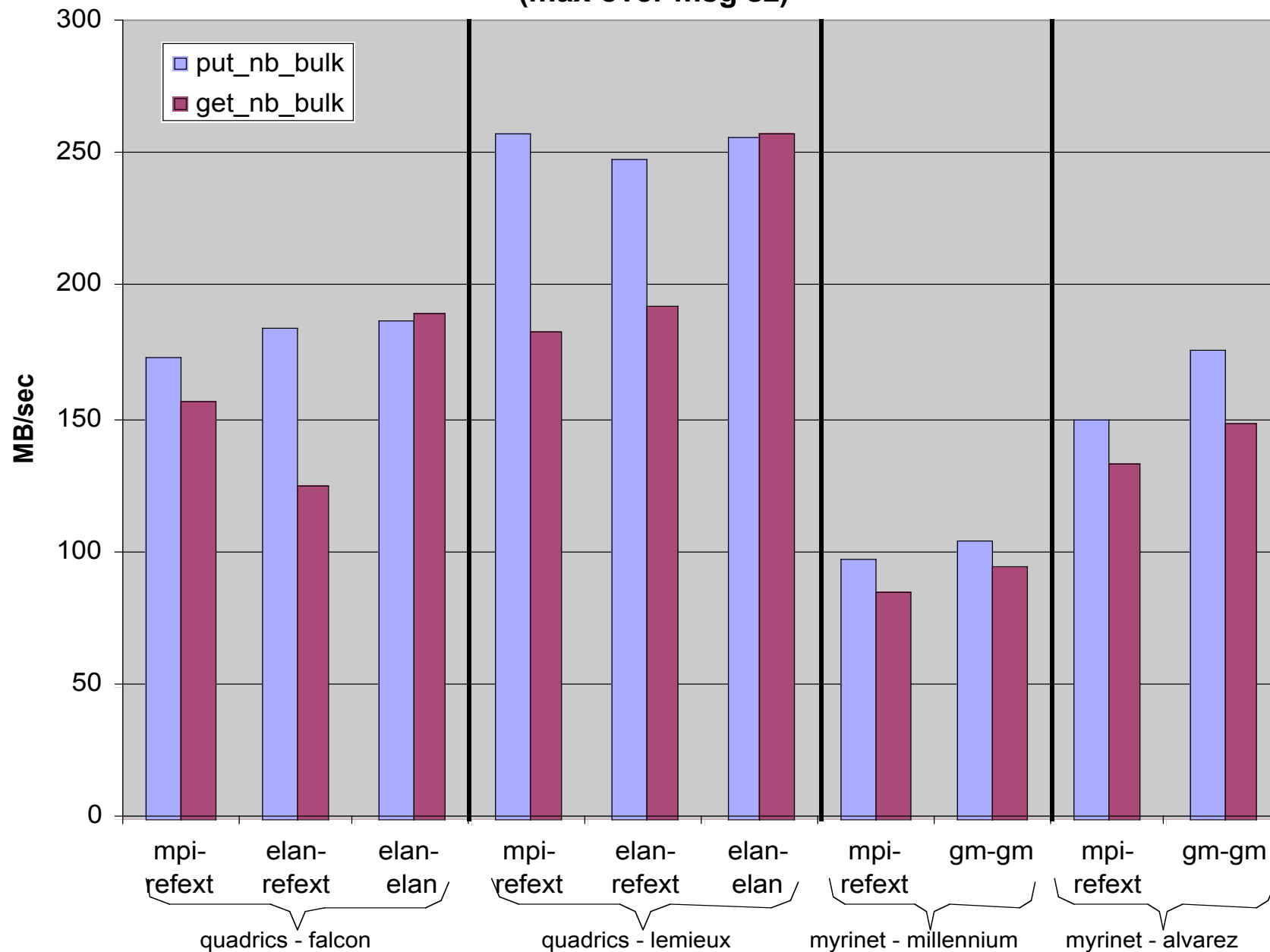# Inv. Throughput (IBM SP, network depth = 8)

- Implies sender overhead.
- The difference from two round-trip latency can be used to estimate wire-delay and receiver overhead

GASNet Put/Get Latency (min over msg sz)

Legend:
- put_nb
- get_nb

y-axis: microseconds (0 to 40)

quadrics -falcon: mpi-refext, elan-refext, elan-elan
quadrics - lemieux: mpi-refext, elan-refext, elan-elan
myrinet - millennium: mpi-refext, gm-gm
myrinet - alvarez: mpi-refext, gm-gm

GASNet Put/Get Bulk Bandwidth
(max over msg sz)

Results

- Explicit and implicit non-blocking get/put performed equally well
- Latency was good but can be tuned further
  - blocking and non-blocking I/O had 7 us overhead over AMMPI
- Bandwidth and throughput were satisfactory
  - Non-blocking I/O performed as well as AMMPI.
- Overall performance is dominated by AMMPI implementation
- Expect better GASNet performance on a native AM implementation

	Blocking	Non-blocking	AMMPI	MPI
Latency (ping-pong round trip)	67 us	67 us	60 us	39 us
Inv throughput (flood: at 16bytes)	79 us	29 us	29 us	8 us
Bandwidth (flood: at 128KB)	113 MB/sec	160 MB/sec	159 MB/sec	242 MB/sec